



UNDERGROUND · CS-440

THE ONLY WAY INTO FLOODED GROUND NOBODY WALKS INTO

Hybrid swim/crawl. Zero visibility. No diver, no radio, no GPS.

RECON · MAPPING · INSPECTION — CULVERTS, STORM SEWERS, INUNDATED TUNNEL

- PATENT PENDING
- EXPORT-CONTROLLED — INTERNATIONAL TRANSFER SUBJECT TO CANADIAN GOVERNMENT PERMITS
- SENSOR CARRIER — NO WARHEAD, NO FUZE, NO ENERGETIC MATERIAL

≥450 MM MINIMUM CULVERT · STORM-SEWER CLASS	~10 M FULLY-SUBMERGED DEPTH CLASS	~0.8 M/S SWIM CRUISE, FLOODED REACHES	0 RADIO LINKS IN ANY GUIDANCE TIER
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OVERVIEW

THE WET-TUNNEL SPECIALIST. THE BRIDGE TO WATER.

Part of the **5-system Underground line** — shares its envelope and doctrine with Badger, Aquifer, Ferret.

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Muskrat CS-440 is a small hybrid swim/crawl platform built for flooded culverts, storm sewers and inundated tunnel sections — ground where no other Underground platform can operate, and where the Water family's Orca AUV is simply oversized for the space. It exists because a person should never have to wade or dive into a dark, current-bearing pipe to find out what is in it.

It is explicitly the joint between two families. Muskrat carries the same no-radio doctrine and the same fibre-or-logged guidance philosophy as Orca, adapted for a tight, dark, debris-choked confined-water environment instead of open water — the same thesis, a different pressure class and a much smaller turning circle.

Family heritage runs underneath it. Canadian Shield's parent group carries three decades of horizontal-directional-drilling heritage in-house — the trade of steering a tool blind through the ground and knowing exactly where it is without a radio link. That trade did not stop at the water's edge; Muskrat is where it meets the flood.

THE CLAIM

SEND THE ROBOT DOWN THE HOLE. NOT THE SOLDIER.

Here the hole is flooded — a storm sewer, a culvert, an inundated tunnel section — and the alternative it replaces is a diver working blind or a person wading a dark pipe by feel. Muskrat goes first, sees in the dark by sonar, and reports back over a line nothing can jam.

HOW IT WORKS

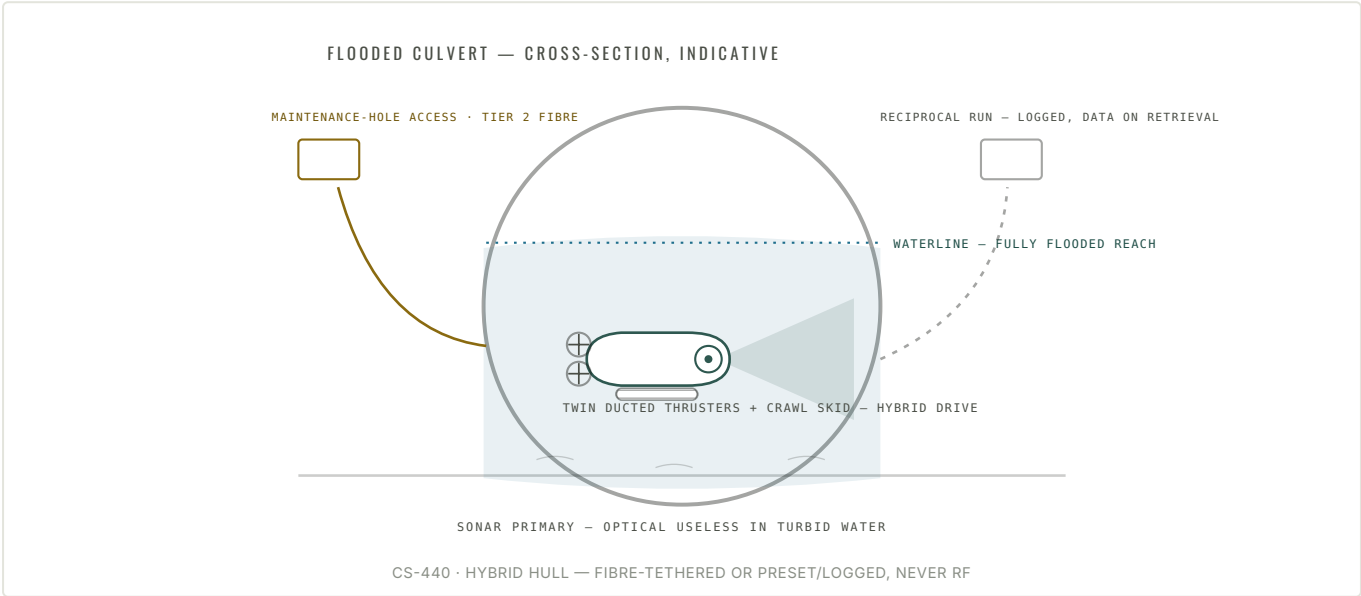
MECHANISM

A HYBRID HULL FOR CONFINED, FLOODED, ZERO-VISIBILITY GROUND

Propulsion is a hybrid: twin ducted thrusters for the flooded reaches, and a tracked/wheeled crawl skid that folds out for the shallow or dry sections the same run often has — a culvert rarely stays one depth end to end.

The water it works in is almost always opaque, so optical cameras are treated as situational, not primary. Forward-looking sonar is the default eye for the flooded run; LIDAR is carried for the above-waterline and dry sections of the same passage where optics can actually see. A water-quality probe rides along where the mission calls for it — contamination and flow-condition sensing is a natural extension of a platform already built to go where the water is worst.

Guidance never argues with the water. A fibre tether carries commands and telemetry in real time, with a human in the loop, for close work and short runs — the workhorse tier. For longer culvert runs where a tether is impractical to pay out or recover, Muskrat runs a preset, logged profile and reports the data on retrieval — Orca's own survey-mission philosophy, carried into a pipe. No radio, ever. No acoustic modem standing in for one. GPS would not reach the water anyway, so the design never asks it to.



SPECIFICATIONS

CAPABILITIES & SPECIFICATIONS

MUSKRAT CS-440	
DIMENSIONS & MASS	
Overall length	~560 mm
Hull envelope diameter	Ø180 mm, thrusters folded
Gross mass	~11 kg
Configuration	Hybrid swim/crawl — twin ducted thrusters + tracked/wheeled crawl skid
PERFORMANCE	
Speed — swim	~0.8 m/s cruise
Speed — crawl	~0.3 m/s cruise
Endurance	~2 h submerged run
Minimum clear passage	≥450 mm class culvert / storm-sewer
Depth rating	Shallow-water class — fully submerged to ~10 m
DRIVE & CONTROL	
Propulsion — swim	Twin ducted thrusters, low-RPM
Propulsion — crawl	Tracked/wheeled crawl skid — shallow & dry sections
PAYLOAD & SENSORS	
Sensor suite	Forward-looking sonar (primary) · LIDAR (dry / above-waterline) · water-quality probe
Payload	Non-kinetic sensor/inspection cartridge — camera, sonar, sampler
SEALING & ENVIRONMENT	
Sealing / ingress protection	IP68-class, shallow-water rated
Design environment	Flooded culverts · storm sewers · inundated tunnel sections · zero visibility
GUIDANCE & COMMUNICATIONS	
Guidance tiers	Fibre-tethered teleop (workhorse) · preset/ logged untethered profile
Communications	Fibre tether, or logged data recovered on retrieval — no radio, no GPS
COMPLIANCE	
Patent status	Patent pending
Export control	Export-controlled — international transfer subject to Canadian government permits; export posture is counsel-first
Classification	Carrier for sensors and inspection cartridges — never a strike platform; no warhead, no fuze, no energetic material
Open-water scope	Orca CS-310 — the Water family half of the same thesis; Muskrat covers the confined, flooded passage

EVERY SPEED AND ENDURANCE FIGURE STATES ITS MODE (SWIM OR CRAWL); THE DEPTH FIGURE STATES ITS CLASS — A CONFINED-WATER PLATFORM, NOT A DEEP-OCEAN ONE. THAT IS HOUSE POLICY, NOT FINE PRINT.

THE TRADES, STATED

NO RADIO. NO GPS. NOT EVEN UNDERWATER, UNDERGROUND.

The house thesis is that the link is the vulnerability — Muskrat carries none. A fibre tether cannot be jammed because there is no spectrum in the loop; a preset/logged run emits nothing at all and reports only after it surfaces. No acoustic modem is dressed up as a wireless substitute. That boundary holds in a flooded pipe exactly as it holds in dry rock.

Muskrat is the platform where two family doctrines meet without contradiction. The Underground family's rule — send the robot down the hole, not the soldier — was written for dry bores and existing tunnels. Muskrat proves it also holds when the hole is flooded: the alternative it replaces is a diver working blind or a person wading a storm sewer by feel, and the doctrine rules that alternative out.

And it is a carrier, never a munition. No warhead, no fuze, no energetic material anywhere in the design, in any cartridge or variant. Muskrat senses, maps and inspects — it does not strike, and it never will.

DEPLOYMENT

A FLOODED RUN, WALKED THROUGH.

One flooded run, walked end to end — illustrative of how the platform is used, not a mission record.

FAMILY CONTEXT

EIGHT PLATFORMS. ONE UNDERGROUND MOAT.

Badger and Aquifer make the hole. Ferret, Mole, the Trembler Line, Muskrat, Gopher and the Farell Pig work holes and passages that already exist — they enter, listen in, swim, crawl or ride. Muskrat's job is the one none of the others can do: go where the passage is flooded, and come back with the picture. See the Orca brochure for the open-water half of the same thesis.

01 · ARRIVAL

DOWN THE MAINTENANCE HOLE, NOT A PERSON

Muskrat inserts at a maintenance hole, a culvert mouth, or a storm-sewer access point — wherever a crew can reach without entering the water itself. For a real-time run the tether is seated and paid out from the surface reel; for a long culvert leg, the mission profile loads and the vehicle goes in untethered. No link check on the untethered leg — there is no link to check.

02 · WORK

SWIM, CRAWL, SENSE, LOG

Muskrat swims the flooded reaches and crawls the shallow or dry ones on the same run, sonar sweeping ahead in water no camera could use. On the fibre, a human sees what the sonar sees, in real time. Off the fibre, the run logs continuously and reports nothing until it is out.

03 · RECOVER

PULLED BACK, OR HOME ON ITS OWN LINE

A tethered run is retrieved by pulling the tether back through the maintenance hole. An untethered run reverses its own logged route and returns to the entry point on a preset reciprocal path, where the data offloads at the surface. Either way, the hull and the picture come home — never a diver, never a person in the water.

THE FAMILY

RELATED SYSTEMS

CS-410 · MAKES THE HOLE

BADGER

With Aquifer, Badger makes the hole — the start of the underground moat the rest of the family works.

CS-411 · MAKES THE HOLE

AQUIFER

The second of the two hole-makers; the other six platforms work holes and passages that already exist.

CS-420 · EXISTING PASSAGES

FERRET

Like Mole, Gopher and the Farell Pig, Ferret works passages that already exist — enter, listen in, crawl or ride.

CS-310 · OPEN WATER

ORCA

The open-water half of the same thesis — the same no-radio, fibre-or-logged philosophy, in a hull too big for the pipe.

Muskrat CS-440 · patent pending · export-controlled — international transfer requires Canadian government permits; export posture is counsel-first. A carrier for sensors and inspection cartridges — never a strike platform: no warhead, no fuze, no energetic material anywhere in the design, in any cartridge or variant. No radio and no GPS in any guidance tier — fibre-tethered or preset/logged only, and no acoustic modem standing in for a radio.



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MUSKRAT · UNDERGROUND · CS-440

Eight platforms. One underground moat.

01

REQUEST A TECHNICAL EXCHANGE

A working session with engineering, not sales — bring your engagement problem, we bring the mechanism.

02

REQUEST THE UNDERGROUND FAMILY DATA PACK

Drawings, tolerances and test basis for Muskrat and its siblings, gated behind export screening.

03

DISCUSS A TRIAL QUANTITY

Tell us end-user, jurisdiction, quantity band and timeline — we respond against your program, not a price list.

SALES

sales@cdnshield.ca

GENERAL

info@cdnshield.ca

WEB

cdnshield.ca

Direct lines, named points of contact and facility details are shared with qualified programs following screening — not withheld, sequenced.

Canadian Shield is a defence and industrial drone company, backed by SIG: four-domain uncrewed systems built for jammed, GPS-denied environments — no-radio by design, manufactured for cost and salvo depth.

Muskrat CS-440

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Product specification R1.0 · 2026-08-15 · © Canadian Shield, a division of SIG (Sustainable Infrastructure Group).